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October 15, 2024, Updated October 20, 2024

[SpaceX launches mega Starship rocket in successful test flight | AP News](#)

The following was posted on LinkedIn on October 15, 2024, in response to the link above.

Truly an inspirational application of 3-D concepts supported by the global spatial data model (GSDM). Additional comments coming soon – see <http://globalcogo.com/catch.pdf>.

These are the additional comments.

The dramatic “catch” of a rocket booster embodies many concepts based on first principles including the geometrical environment as described by the global spatial data model (GSDM). See www.globalcogo.com and www.tru3d.xyz.

I was very impressed when watching the video of the SpaceX rocket booster returning to the launch pad. There is much I don’t know about details of their success but, applying principles of reverse engineering within concepts of the GSDM, it is easy to conjecture the following.

Success of the catch relied on:

1. The location of the target (launch pad) had to be known – feature of a high-definition map.
2. The instantaneous location of the booster had to be known in real time.
 - a. Requires very fast computers.
 - b. Determined by GNSS.
 - c. Supplemented by inertial positioning.
3. Predicting the trajectory of the booster based on:
 - a. Equations of motion subject to –
 - i.) changing mass due to burning fuel.
 - ii.) changing gravity due to changing elevation.
 - b. Strategic corrections applied with thruster firings.
4. Knowing the positional accuracy of both target and booster.
 - a. Target - within the “global” ECEF system – network accuracy.
 - b. With respect to the spatial separation between them – local accuracy.
5. Rotation matrices used to reconcile the orientation of . . .
 - a. Target (launch pad) – presumably stationery with respect to ECEF.
 - b. Booster in multiple axes as determined from observations by . . .
 - i.) GNSS in true 3-D.
 - ii.) Inertial measuring unit in pseudo 3-D.

Notes:

1. Monitoring the “catch” is computationally intensive but uses “standard” equations.
2. This project bears some similarity to surveying with drones.